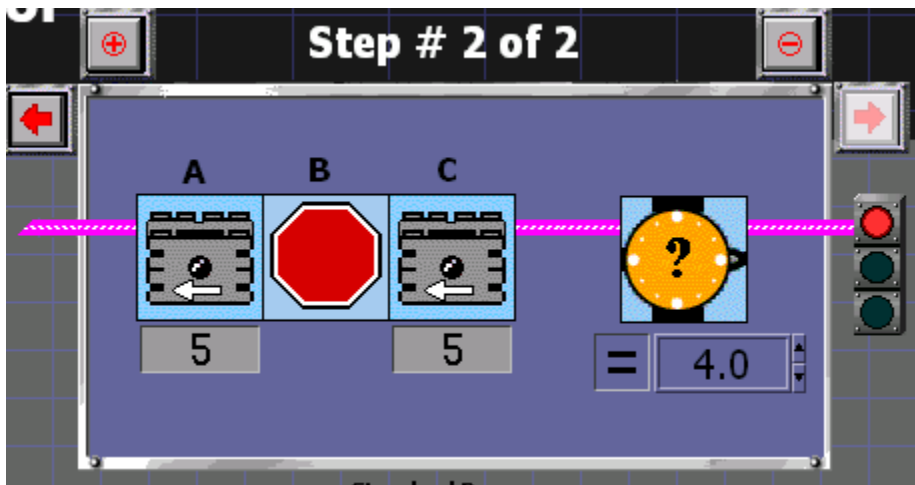
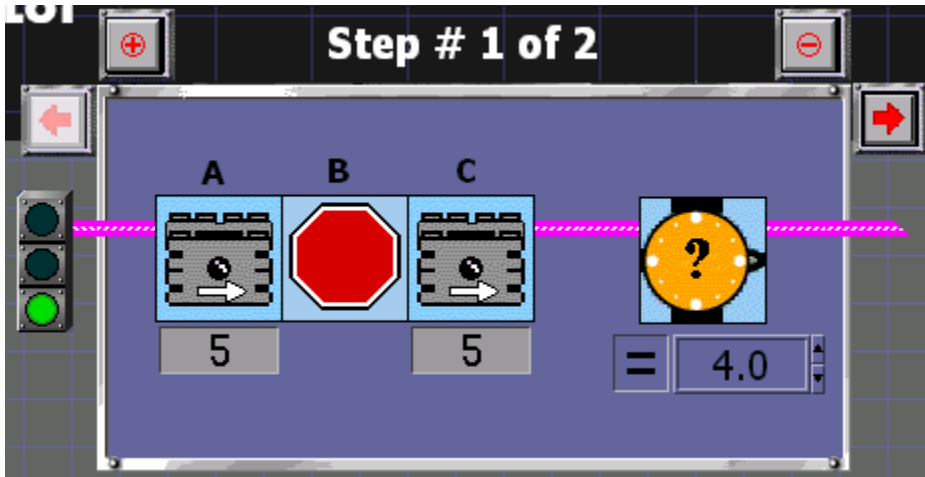
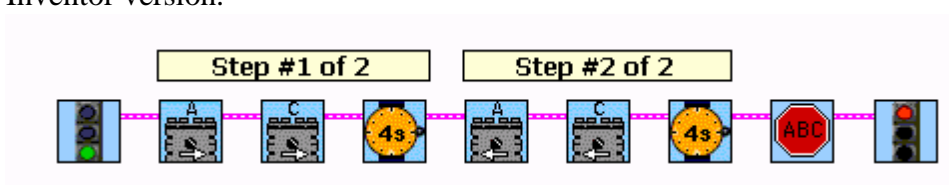


# There and Back: Using Timing

Pilot version:



Inventor version:



This program makes the Robot go forward 4 seconds then reverses the motors for 4 seconds, and then it stops all Output Ports.